

Uitwerking Final Exam Kwantumfysica 1 27 APRIL 2007

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Problem 1

- a) Time-independent Schrödinger equation for a one-dimensional particle, in x-representation:

$$\left[-\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} + V(x) \right] \varphi(x) = E \varphi(x) \Rightarrow$$

$$\frac{\partial^2}{\partial x^2} \varphi(x) = -\frac{2m(E-V)}{\hbar^2} \varphi(x)$$

This differential equation has solutions of the form $\varphi(x) = e^{ikx}$ (plane waves with wave number k)

This is consistent with the Schrödinger equation for

$$k = \frac{\sqrt{2m(E-V)}}{\hbar} \Rightarrow k_i = \frac{\sqrt{2m(E-V_i)}}{\hbar}$$

- b) During the scatter event $\varphi(x)$ should have $\frac{\partial \varphi}{\partial x}$ continuous at $x=0$, where $\varphi(x)$ the wavefunction of the particle. Here $\varphi(x)$ is:

In region 1, $\varphi(x) = \varphi_1(x) = A e^{ik_1 x} + B e^{-ik_1 x}$
(an incoming and reflected plane wave)

In region 2, $\varphi(x) = \varphi_2(x) = C e^{ik_2 x}$
(only a transmitted plane wave)

A description of these plane waves only is appropriate because the uncertainty in velocity is very small.

Working this out gives

$$\begin{cases} \varphi_1(0) = \varphi_2(0) \\ \frac{\partial \varphi_1(0)}{\partial x} = \frac{\partial \varphi_2(0)}{\partial x} \end{cases} \Rightarrow \begin{cases} A + B = C \\ k_1 A - k_1 B = k_2 C \end{cases} \Rightarrow$$

Solve for B and C normalized to A

$$\begin{cases} \frac{B}{A} - \frac{C}{A} = -1 \\ -\frac{k_2}{k_1} \frac{C}{A} - \frac{B}{A} = -1 \end{cases} \Rightarrow \begin{cases} \frac{B}{A} = \frac{1 - k_2/k_1}{1 + k_2/k_1} \\ \frac{C}{A} = \frac{2}{1 + k_2/k_1} \end{cases}$$

The probability for the particle to be reflected is then $\left| \frac{B}{A} \right|^2$, which gives

$$R = \left| \frac{B}{A} \right|^2 = \left| \frac{1 - k_2/k_1}{1 + k_2/k_1} \right|^2 \Rightarrow$$

$$R = \left| \frac{1 - \sqrt{\frac{E_0 - V_2}{E_0 - V_1}}}{1 + \sqrt{\frac{E_0 - V_2}{E_0 - V_1}}} \right|^2$$

- c) With $V_2 = V_1 - V_0$ follows from b)

$$R = \left| \frac{1 - \sqrt{\frac{(E_0 - V_1) + V_0}{E_0 - V_1}}}{1 + \sqrt{\frac{(E_0 - V_1) + V_0}{E_0 - V_1}}} \right|^2$$

Only differences in energy matter, absolute values of energy have little meaning.

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d) Use c) and substitute

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| case | $(E_0 - V_1)$ | V_0 | R |
|-----------------|---------------|------------|-------|
| $V_2 = 0.5 V_1$ | V_1 | $0.5 V_1$ | 0.01 |
| $V_2 = 1 V_1$ | V_1 | 0 | 0 |
| $V_2 = 1.5 V_1$ | V_1 | $-0.5 V_1$ | 0.029 |

$$\boxed{V_2 = 0.5 V_1} \quad R = \left| \frac{1 - \sqrt{1.5}}{1 + \sqrt{1.5}} \right|^2 \approx 0.01$$

$$\boxed{V_2 = V_1} \quad R = \left| \frac{1 - \sqrt{1}}{1 + \sqrt{1}} \right|^2 = 0$$

$$\boxed{V_2 = 1.5 V_1} \quad R = \left| \frac{1 - \sqrt{0.5}}{1 + \sqrt{0.5}} \right|^2 \approx 0.029$$

Problem 2

a) Normalized if $\int_{-\infty}^{\infty} |\psi(x)|^2 dx = 1$

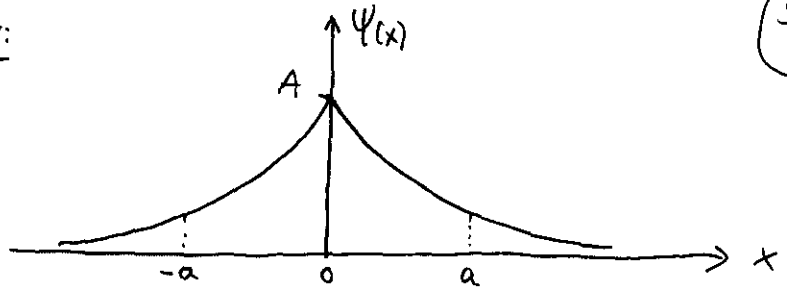
$$\int_{-\infty}^{\infty} |\psi(x)|^2 dx = 2A^2 \int_0^{\infty} e^{-2x/a} dx = -\frac{a}{2} 2A^2 \left[e^{-\frac{2x}{a}} \right]_0^{\infty} \\ = -a A^2 (0 - 1) = a A^2 = 1 \Rightarrow A = \sqrt{\frac{1}{a}}$$

b) Answer is $\psi(x)$ in k -representation \Rightarrow

$$\begin{aligned} \bar{\psi}(k) &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \psi(x) e^{-ikx} dx \\ &= \frac{A}{\sqrt{2\pi}} \int_{-\infty}^0 e^{+x/a} e^{-ikx} dx + \frac{A}{\sqrt{2\pi}} \int_0^{\infty} e^{-x/a} e^{-ikx} dx \\ &= \frac{A}{\sqrt{2\pi}} \int_{-\infty}^0 e^{(\frac{1}{a} - ik)x} dx + \frac{A}{\sqrt{2\pi}} \int_0^{\infty} e^{-(\frac{1}{a} + ik)x} dx \\ &= \frac{A}{\sqrt{2\pi}} \frac{1}{(\frac{1}{a} - ik)} \left[e^{(\frac{1}{a} - ik)x} \right]_{-\infty}^0 + \frac{A}{\sqrt{2\pi}} \frac{-1}{(\frac{1}{a} + ik)} \left[e^{-(\frac{1}{a} + ik)x} \right]_0^{\infty} \\ &= \frac{A}{\sqrt{2\pi}} \frac{1}{\frac{1}{a} - ik} (1 - 0) + \frac{A}{\sqrt{2\pi}} \frac{-1}{(\frac{1}{a} + ik)} (0 - 1) \\ &= \frac{A}{\sqrt{2\pi}} \left(\frac{1}{\frac{1}{a} - ik} + \frac{1}{\frac{1}{a} + ik} \right) = \frac{A}{\sqrt{2\pi}} \left(\frac{\frac{1}{a} + ik}{\frac{1}{a^2} + k^2} + \frac{\frac{1}{a} - ik}{\frac{1}{a^2} + k^2} \right) \\ &= \frac{A}{\sqrt{2\pi}} \left(\frac{2 \frac{1}{a}}{\frac{1}{a^2} + k^2} \right) = \frac{2aA}{\sqrt{2\pi}} \cdot \frac{1}{1 + a^2 k^2} \Rightarrow \text{with } A = \frac{1}{\sqrt{a}} \\ \bar{\psi}(k) &= \frac{2\sqrt{a}}{\sqrt{2\pi}} \cdot \frac{1}{1 + a^2 k^2} \end{aligned}$$

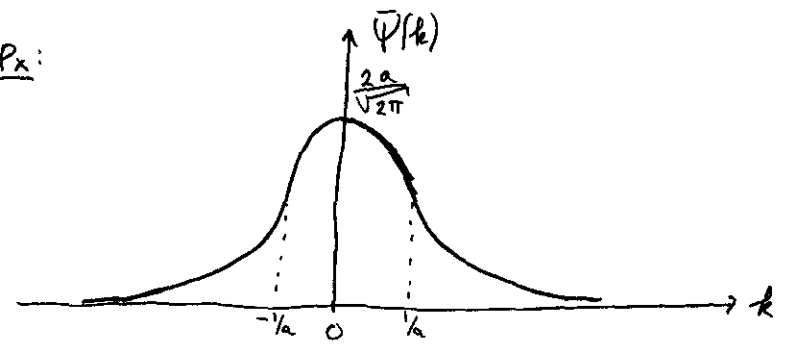
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Δx :



$\Psi(x)$ drops to $\frac{1}{2}A$ for $x = \pm a \Rightarrow$ Width of this state $\approx a \Rightarrow \Delta x \approx a$

Δp_x :



$\Psi(k)$ drops to $\frac{1}{2} \cdot \frac{2a}{\sqrt{2\pi}}$ for $k = \pm \frac{1}{a} \Rightarrow$ Width of this state $\approx \frac{1}{a} \Rightarrow \Delta k \approx \frac{1}{a}$

$p_x = \hbar k \Rightarrow \Delta p_x \approx \frac{\hbar}{a}$

Heisenberg: $\Delta x \Delta p_x \geq \frac{\hbar}{2}$

Here we find $\Delta x \cdot \Delta p_x \approx a \cdot \frac{\hbar}{a} \approx \hbar \Rightarrow$ No violation

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d) Velocity is proportional to k , $v = \frac{p_x}{m} = \frac{\hbar k}{m} \Rightarrow$

Use k -representation to evaluate this probability

$$P_{40-50} = \int_{k_{40}}^{k_{50}} |\Psi(k)|^2 dk = \int_{k_{40}}^{k_{50}} \left(\frac{2k}{\sqrt{2\pi}} \right)^2 \left(\frac{1}{1+a^2 k^2} \right)^2 dk$$

$$= \frac{2a}{\pi} \int_{k_{40}}^{k_{50}} \left(\frac{1}{1+a^2 k^2} \right) dk = \frac{2a}{\pi} \left[\frac{1}{2} \frac{k}{1+a^2 k^2} + \frac{1}{2} \frac{\arctan(ak)}{a} \right]_{k_{40}}^{k_{50}}$$

$$= \frac{1}{\pi} \left[\frac{ak}{1+a^2 k^2} + \arctan(ak) \right]_{k_{40}}^{k_{50}}, \text{ with}$$

$a k_{40} = \frac{a m v_{40}}{\hbar} = \frac{1 \cdot 10^{-9} \cdot 9.1 \cdot 10^{-31} \cdot 40 \cdot 10^3 \text{ m kg m/s}}{1.055 \cdot 10^{-34} \text{ Js}} = 0.345$

$a k_{50} = \frac{a m v_{50}}{\hbar} = \frac{1 \cdot 10^{-9} \cdot 9.1 \cdot 10^{-31} \cdot 50 \cdot 10^3 \text{ m kg m/s}}{1.055 \cdot 10^{-34} \text{ Js}} = 0.431$

$\Rightarrow P_{40-50} = \frac{1}{\pi} \left(\frac{0.431}{1+(0.431)^2} - \frac{0.345}{1+(0.345)^2} + \arctan(0.431) - \arctan(0.345) \right)$

$= 0.041 \Rightarrow \approx 4\%$

Problem 3

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a) E_g and E_e should be consistent with $|\varphi_g\rangle$ and $|\varphi_e\rangle$ in the Schrödinger equation $\hat{H}|\varphi_i\rangle = E_i|\varphi_i\rangle$

For $\begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix}$ this gives

$$\begin{pmatrix} E_0 & T \\ T & E_0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = E_+ \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} \Rightarrow E_+ = E_0 + T$$

For $\begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix}$ this gives

$$\begin{pmatrix} E_0 & T \\ T & E_0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix} = E_- \begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix} \Rightarrow E_- = E_0 - T$$

Given that T real and $T < 0$, it must be that

$$\begin{cases} E_g = E_+ = E_0 + T, & \text{for } |\varphi_g\rangle \\ E_e = E_- = E_0 - T, & \text{for } |\varphi_e\rangle \end{cases}$$

$$b) \langle \varphi_g | \varphi_g \rangle = \left(\frac{1}{\sqrt{2}} \quad \frac{1}{\sqrt{2}} \right) \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = \frac{1}{2} + \frac{1}{2} = 1 \Rightarrow \text{Normalized}$$

$$\langle \varphi_e | \varphi_e \rangle = \left(\frac{1}{\sqrt{2}} \quad -\frac{1}{\sqrt{2}} \right) \begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix} = \frac{1}{2} + \frac{1}{2} = 1 \Rightarrow \text{Normalized}$$

$$\langle \varphi_e | \varphi_g \rangle = \left(\frac{1}{\sqrt{2}} \quad -\frac{1}{\sqrt{2}} \right) \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = \frac{1}{2} - \frac{1}{2} = 0 \Rightarrow \text{Orthogonal}$$

c) For \hat{H}_0 :

$$[\hat{A}, \hat{H}_0] = \hat{A}\hat{H}_0 - \hat{H}_0\hat{A} = \begin{pmatrix} -a & 0 \\ 0 & a \end{pmatrix} \begin{pmatrix} E_0 & 0 \\ 0 & E_0 \end{pmatrix} - \begin{pmatrix} E_0 & 0 \\ 0 & E_0 \end{pmatrix} \begin{pmatrix} -a & 0 \\ 0 & a \end{pmatrix} \\ = \begin{pmatrix} -aE_0 & 0 \\ 0 & aE_0 \end{pmatrix} - \begin{pmatrix} -aE_0 & 0 \\ 0 & aE_0 \end{pmatrix} = 0 \Rightarrow \hat{A} \text{ and } \hat{H}_0 \text{ commute}$$

For \hat{A} :

$$[\hat{A}, \hat{H}] = \hat{A}\hat{H} - \hat{H}\hat{A} = \begin{pmatrix} -a & 0 \\ 0 & a \end{pmatrix} \begin{pmatrix} E_0 & T \\ T & E_0 \end{pmatrix} - \begin{pmatrix} E_0 & T \\ T & E_0 \end{pmatrix} \begin{pmatrix} -a & 0 \\ 0 & a \end{pmatrix} \\ = \begin{pmatrix} -aE_0 & -aT \\ aT & aE_0 \end{pmatrix} - \begin{pmatrix} -aE_0 & aT \\ -aT & aE_0 \end{pmatrix} = \begin{pmatrix} 0 & -2aT \\ -2aT & 0 \end{pmatrix} \neq 0$$

$\Rightarrow \hat{A}$ and \hat{H} do not commute.

d) \hat{A} is a diagonal matrix, so the eigenvalues are on the diagonal. \hat{H}_0 and \hat{A} commute (but \hat{H}_0 degenerate), so the eigenvectors of \hat{A} are the same or a linear superposition of those of \hat{H}_0 .

$$\hat{A}|\varphi_i\rangle = \pm a|\varphi_i\rangle \Rightarrow$$

$$\begin{pmatrix} -a & 0 \\ 0 & a \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = +a \begin{pmatrix} 0 \\ 1 \end{pmatrix} \text{ is consistent for } |\varphi_R\rangle \Leftrightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

\Rightarrow eigenvalue $+a$ has eigenvector $|\varphi_R\rangle$

$$\begin{pmatrix} -a & 0 \\ 0 & a \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = -a \begin{pmatrix} 1 \\ 0 \end{pmatrix} \text{ is consistent for } |\varphi_L\rangle \Leftrightarrow \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

\Rightarrow eigenvalue $-a$ has eigenvector $|\varphi_L\rangle$

c) Ground state of \hat{H} is $|\varphi_g\rangle = \frac{1}{\sqrt{2}}(|\varphi_L\rangle + |\varphi_R\rangle)$ 9/11

So, a measurement of \hat{A} can give both $+a$ and $-a$ as answer

| measurement outcome | Probability | state after measurement |
|---------------------|---|-------------------------|
| $-a$ | $ \langle\varphi_L \varphi_g\rangle ^2 = \frac{1}{2}$ | $ \varphi_L\rangle$ |
| $+a$ | $ \langle\varphi_R \varphi_g\rangle ^2 = \frac{1}{2}$ | $ \varphi_R\rangle$ |

$$f) |\psi\rangle = \sqrt{\frac{1}{3}}|\varphi_g\rangle + \sqrt{\frac{2}{3}}|\varphi_e\rangle = \left(\sqrt{\frac{1}{6}}|\varphi_L\rangle + \sqrt{\frac{1}{6}}|\varphi_R\rangle\right) + \left(\sqrt{\frac{2}{6}}|\varphi_L\rangle - \sqrt{\frac{2}{6}}|\varphi_R\rangle\right)$$

$$= \frac{1+\sqrt{2}}{\sqrt{6}}|\varphi_L\rangle + \frac{1-\sqrt{2}}{\sqrt{6}}|\varphi_R\rangle \Rightarrow \text{Both } |\varphi_L\rangle \text{ and } |\varphi_R\rangle$$

have non-zero probability amplitude, so a measurement can give both $+a$ and $-a$ as answer.

Probability for $-a$ is $|\langle\varphi_L|\psi\rangle|^2$,
for $+a$ is $|\langle\varphi_R|\psi\rangle|^2$

| measurement outcome | Probability | state after measurement |
|---------------------|--|-------------------------|
| $-a$ | $\left(\frac{1+\sqrt{2}}{\sqrt{6}}\right)^2$ | $ \varphi_L\rangle$ |
| $+a$ | $\left(\frac{1-\sqrt{2}}{\sqrt{6}}\right)^2$ | $ \varphi_R\rangle$ |

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g) The state is $|\varphi_L\rangle = \frac{1}{\sqrt{2}}(|\varphi_g\rangle + |\varphi_e\rangle)$ 10/11

since $|\varphi_g\rangle = \frac{1}{\sqrt{2}}(|\varphi_L\rangle + |\varphi_R\rangle)$ and $|\varphi_e\rangle = \frac{1}{\sqrt{2}}(|\varphi_L\rangle - |\varphi_R\rangle)$

h) $\langle\varphi_g|\hat{A}|\varphi_g\rangle = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} -a & 0 \\ 0 & a \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = 0 \Rightarrow$ expectation value for position is zero for system in state $|\varphi_g\rangle$

$\langle\varphi_e|\hat{A}|\varphi_e\rangle = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} -a & 0 \\ 0 & a \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = 0 \Rightarrow$ expectation value for position is zero for system in state $|\varphi_e\rangle$

$\langle\varphi_g|\hat{A}|\varphi_e\rangle = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} -a & 0 \\ 0 & a \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = -a$

$\langle\varphi_e|\hat{A}|\varphi_g\rangle = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} -a & 0 \\ 0 & a \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = -a$

When the system is in a superposition of $|\varphi_g\rangle$ and $|\varphi_e\rangle$ the expectation value for position can be different from zero.

i) State at $t=0$ denoted as $|\psi_0\rangle = |\varphi_L\rangle = \frac{1}{\sqrt{2}}(|\varphi_g\rangle + |\varphi_e\rangle)$

For investigating time evolution of \hat{A} describe the state of the system as a superposition of energy eigen states.

$$\langle\hat{A}(t)\rangle = \langle\psi(t)|\hat{A}|\psi(t)\rangle = \langle\psi_0|U^\dagger \hat{A} U|\psi_0\rangle$$

with $U = e^{-\frac{i}{\hbar}\hat{H}t} \Rightarrow$

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$$\langle \hat{A}(t) \rangle = \frac{1}{2} (\langle \varphi_g | + \langle \varphi_e |) \hat{U}^\dagger \hat{A} \hat{U} (| \varphi_g \rangle + | \varphi_e \rangle)$$

$$= \frac{1}{2} \left(e^{+i\omega_g t} \langle \varphi_g | + e^{+i\omega_e t} \langle \varphi_e | \right) \hat{A} \left(e^{-i\omega_g t} | \varphi_g \rangle + e^{-i\omega_e t} | \varphi_e \rangle \right)$$

$$= \frac{1}{2} \left(\langle \varphi_g | \hat{A} | \varphi_g \rangle + \langle \varphi_e | \hat{A} | \varphi_e \rangle + e^{+i(\omega_g - \omega_e)t} \langle \varphi_g | \hat{A} | \varphi_e \rangle + e^{+i(\omega_e - \omega_g)t} \langle \varphi_e | \hat{A} | \varphi_g \rangle \right)$$

$$= \frac{1}{2} \left(0 + 0 + e^{-i(\omega_e - \omega_g)t} (-a) + e^{+i(\omega_e - \omega_g)t} (-a) \right)$$

$$= -\frac{1}{2} a \cdot 2 \cos((\omega_e - \omega_g) t)$$

$$= -a \cos((\omega_e - \omega_g) t)$$

where we used $\omega_e = \frac{E_e}{\hbar}$ and $\omega_g = \frac{E_g}{\hbar}$

$$E_e - E_g = \underbrace{-2T}_{> 0} \Rightarrow$$

$$\langle \hat{A}(t) \rangle = -a \cos\left(\frac{|2T|}{\hbar} t\right)$$

The system oscillates between the two wells, from position $-a$ to a and back, and starts (as it should) indeed at $-a$ for $t=0$.

The frequency of the oscillations is $\frac{E_e - E_g}{\hbar} = \frac{|2T|}{\hbar}$
angular